Prediction of Protein Residue Contact Using Support Vector Machine

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Abstract. Prediction of protein residue contact is one of the important two-dimensional prediction tasks in protein structure prediction. The residue contact map of protein contains information which represents three-dimensional conformation of protein. However the accuracy of the prediction is dependent on the type of protein information used to distinguish between contacts or non-contacts. According to CASP (Critical Assessment of Techniques of Protein Structure Prediction) the accuracy of protein contact map prediction is still low due to the behaviour of the predictors developed where the predictors only effective against specific type of protein structure. In order to further improve the performance of the predictor, effective features must be identified and used. Therefore, this research is conducted to determine the effectiveness of the existing features used in protein contact map prediction.

Keywords: protein residue contact map, support vector machine, protein structure prediction.

1 Introduction

Bioinformatics is defined as a field of science that involve the application of statistics and computer science in the field of biology. It is an emerging field undergoing rapid growth in the past few decades. Bioinformatics at first is applied in the creation and maintenance of database of biological information and currently also applied in tasks like interpretation and analysis of biological data includes deoxyribonucleic acid (DNA) sequences, ribonucleic acid (RNA) sequences, protein structures, protein sequences and protein domains which referred as computational biology. The branch of bioinformatics that consists of the analysis and prediction of three dimensional structures of biological macromolecules such as DNA, RNA and proteins referred as structural bioinformatics. In structural bioinformatics, one of the challenges is the prediction of protein structure.

Protein is one of the most important compounds in human body. Function of a protein is defined by its structure. Protein structures are divided into few categories such as primary structure, secondary structure, tertiary structure, and quaternary structure. A protein consists of more than one linear chain of amino acids that

further fold into polypeptides of different structures and features. Protein structure prediction has played an important role in protein design which is essential is several fields for instance medicine. In protein structure prediction, different information of protein has been used and one of them is protein contact map which is used in this research. Protein contact map is a compact representation of three-dimensional conformations of a protein. A contact map is a two-dimensional Boolean matrix representation of protein structure, each of the dimensions is represented by residue number, while the value is true when the corresponding residues are spatial neighbours and false otherwise [2]. Protein contact map is binary symmetric matrices where non-zero values represent the residue in contact [3] that is shown in Fig. 1.

According to Fig. 1, Secondary structures are highlighted along the both axis. Both α-helices and β-strands represented by black and grey respectively. While on the left side, the structural protein features are shown: (a) Anti-parallel sheet contacts; (b) parallel sheet contacts; (c) contacts between helical regions. Generally, a residue pair considers as a contact when the distance between the residues within a pair is below a defined distance threshold. The distance threshold is calculated in angstrom (Å) which measure as 0.1 nanometre or 1 x 10-10 metres. In CASP (Critical Assessment of Techniques for Protein Structure Prediction), default distance threshold used for assessment is 8Å which is same as the threshold used in this research.
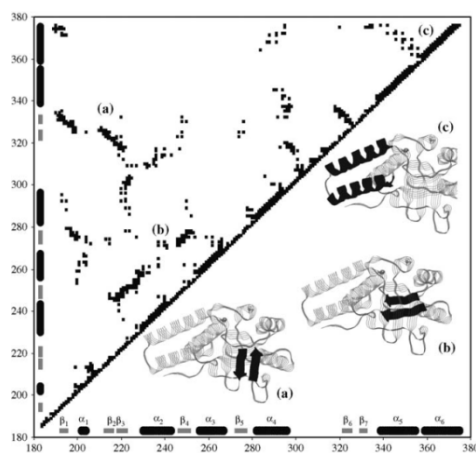

Fig. 1. Example of contact map of HSP-60 protein fragment

Based on the researches done in the past decade, many techniques and algorithms have been developed to predict contact map of a protein. Among those methods, machine learning algorithms have been widely used such as support vector machine (SVM). Machine learning is an artificial intelligent technique where it is a scientific discipline that is concern about design and development of algorithms that allows computer to learn and evolve behaviours based on the empirical data. It learns to recognize complex patterns thus make decision to gain useful output. In this research,

SVM has been used and implemented. SVM is a supervised learning method that analyses and recognizes pattern for classification and regression. SVM constructs a hyperplane or a set of hyperplanes in high or infinite dimensional space for classification and regression.

Since the prediction of protein contact map is significant in contributing the three-dimensional structure prediction of protein, refer to the state of art of protein contact map prediction, one of the main concerns is the performance issues of several predictors for protein contact map. According to the CASP (Critical Assessment of Techniques of Protein Structure Prediction), the accuracy and the coverage of the prediction of protein contact map are still low and performance varies with the type of structure of the tested protein. In fact, many of the predictors that had been developed tend to predict different correct contacts with implementation of different types of information obtained from protein such as protein profile, predicted secondary structure, solvent accessibility and so forth. Therefore consensus combination of predictors may lead to a better accuracy in protein contact map prediction. To date, researchers are still working on protein contact map prediction in order to enhance the predictor to obtain better and more accurate prediction. Besides, challenges also faced during the prediction of long sequence with many non-local contacts, non-local contacts which had appeared to be a problem because the global topology of the proteins is defined by non-local contacts (also known as long range-contacts) but the methods developed so far are more accurate on local contacts only [2].

This research concentrate in the performance related problem faced in the protein contact map prediction and thus with the use of support vector machine (SVM) method plus different combination of features, studies and experiments have been done in order to identify and determine the effectiveness of the features used in the prediction.

In this paper, details regarding the dataset and the features used as well as the methods are presented in section 2 while results and analysis are discussed and presented in section 3. Conclusion of this research is outlined in section 4.

2   Materials and Methods

2.1   Dataset

The dataset used in this research consist of 424 proteins and 48 proteins for both training and testing set respectively. This dataset had been used in previous research [1] which consist of information regard to the particular protein such as predicted secondary structure and predicted solvent accessibility generated from SSpro [4], protein sequence, beta partners as well as three-dimensional coordinates of alpha carbon for each residue in the protein. The dataset is redundancy reduced where the pairwise sequence identity of two sequences is less than 25%. Fig. 2 shows the example format of one of the data entry in the dataset.

```
1EJGA
46
T  T  A  B  P  S  I  V  A  R  S  N  F  N  V  C  R  L  P  G  T  P  E  A
C  C  C  C  C  C  E  E  E  C  C  C  E  E  E  C  C  C  C  C  H  H  H  H  C  C  C  C  E  E  E  C  C  C  C  C  C  C  C  C
0  34 33 0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0
0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0  0
50 50 10 10 50 50 50 10 50 50 10 10 10 10 10 10 10 50 50 50 50 10 10 10 10 50 10 10 50 10
16.9 12.8 4.2    13.9 11.5 5.9    13.6 10.7 9.6    10.7 8.9 11.3    9.5 9.1 14.9    8.8 5.3 15.2
```

Fig. 2. Example of the dataset format

2.2   Input Features

This research is to construct different prediction models that consist of different combination of features [1] in order to analyze and compare the effectiveness of the features implemented in the prediction model. There are total of five different kinds of features applied in this research which are local window feature, pairwise information feature, central segment window feature, segment average information feature, and protein information feature. These features consist of different information extracted from the dataset proteins including predicted secondary structure and solvent accessibility as well as the amino acid composition of the corresponding protein.

Local window feature is a 9-residue window feature which centered at each residue in each potential residue pair at which the distance of the residue in the pair is not less than the separation value set. In this features, each position within the window, there are 27 inputs which include 21 inputs for amino acids plus a gap, 3 inputs for predicted secondary structure (helix, coil, and sheet), 2 for the predicted solvent accessibility (exposed and buried) and 1 for the entropy. So this feature will have a size of 486.

In pairwise information feature, for each pair of position (i,j) in a multiple sequence alignment, 7 inputs are calculated, one input corresponds to the mutual information of the profiles of the two positions $\sum_{kl} p_{kl} \log(p_{kl}/(p_k p_l))$, where p_{kl} is the empirical probability of residues (or gap) k and l appearing at the two positions i and j simultaneously. While p_k and p_l refer to the probability of appearance of residues k and l respectively. Another two inputs are computed using cosine and correlation and one input for the amino acid type. Finally the last three inputs are regard to the pairwise potential values from three different pairwise potentials which are Levitt's pairwise potential [5], Jernigan's pairwise potential [6] and Braun's pairwise potential [7] for the residue pairs in the target sequence. This feature has a size of 16.

Third is the central segment window feature where this feature has a window size of 5 which locate at the position of (i+j)/2 which is the center of the potential residue pair. For each position of the window, 27 inputs are used same as in the local window features which are 21 for amino acids plus a gap, 3 for predicted secondary structure, 2 for predicted solvent accessibility, 1 for the entropy. Therefore, central segment window feature has a size of 135. Another similar feature which is segment average information feature also using the information extracted from the segment between the residue pair. This feature has a size of 42 and it consist the information about the predicted secondary structure, solvent accessibility and the segment length

information.   Lastly is the protein information feature.   This feature has a size of 30. In this feature, the global amino acid composition, secondary structure, and relative solvent accessibility of the target sequence are calculated.

2.3   Construction of Prediction Models

This research combines different features into several combinations and used to construct several prediction models. In order to compare and analyse the effectiveness of the features and with the availability of high performance computers from Centre of Information and Communication Technology (CICT) UTM, a total of ten prediction models with different combination pairs of features are constructed.   Table 1 shows the ten prediction models that constructed in this research.

Table 1. Prediction models with corresponding features and size

Model	Features	Size
1	Pairwise Information + Local Window	502
2	Pairwise Information + Central Segment Window	151
3	Pairwise Information + Segment Average Information	58
4	Pairwise Information + Protein Information	46
5	Local Window + Central Segment Window	621
6	Local Window + Segment Average Information	528
7	Local Window + Protein Information	516
8	Central Segment Window + Segment Average Information	177
9	Central Segment Window + Protein Information	165
10	Segment Average Information + Protein Information	72

The process of the construction of the prediction models consists of two major steps:

Step 1. Generation of the SVM input for all the combination of features for the training set proteins. In this steps, corresponding information that needed are generated according to the feature involved and result in generation of an input data with SVM compatible format. This process continues executed on the protein sequence in the dataset and append to a single output file. Fig. 3 shows the process to generate SVM input features file.

Step 2. The SVM compatible input files generated is then used in the SVM learning process using SVM Light and generates the prediction models.
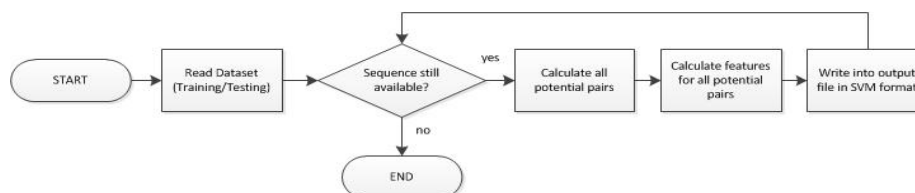

Fig. 3. Process of generating SVM input features

2.4   Learning Using Support Vector Machine

Support vector machines (SVMs) are used to predict an input feature vector which associated with a pair of residues to see if the two residues are in contact (positive) or not (negative). SVM provides several of classification and regression method that uses linear to non-linear way to solve corresponding problem which is controlled by the kernel methods. Kernel methods or kernel functions can re-map the data points into a higher dimensionality feature space solving the problem that are not solvable using linear method.

One of the key property of kernel method is the embedding does not need to be given in explicit form. Given a set of training data points, $S = S^+ \cup S^-$ where S^+ represent the positive samples and S^- represent the negative samples, using the theory of risk minimization, support vector machines learn a classification function $f(x)$ as follow where a_i are non-negative weights and b is the bias. $K(x, x_i)$ is the kernel method used, x_i is the training data points and x is the target data point that is predicted to be positive or negative by taking the sign of $f(x)$.

$$f(x) = \sum_{x_i \in S^+} a_i K(x, x_i) - \sum_{x_i \in S^-} a_i K(x, x_i) + b \tag{1}$$

In this research, radial basis function (RBF) kernel is used in this research to train the prediction models. The RBF kernel is used with the gamma parameter (γ) set to 0.025 which is same as the previous setting [3]. This is because this will ease the comparison of the results later. The RBF kernel can be presented by following

$$K(x, y) = e^{-\gamma \|x - y\|^2} \tag{2}$$

2.5   Performance Measurement

In order to justify the results obtained and the performance of the prediction models, data are compared among the prediction models in terms of prediction performance. In this research, the performance is measured by accuracy and coverage where accuracy is the number of correct predictions per total number of predictions; its value shows the ability of the prediction model to get correct prediction out of the total number of prediction. Higher accuracy implies that the models are able to get more correct prediction. Meanwhile for coverage is the number of correct predictions per total number of true contacts. This parameter is similar to the sensitivity, where it shows the ability of the prediction model to identify true contacts. Higher value of sensitivity implies that the percentage of the true contacts identified is high as well. In this research, both measurements are correlated to each other, if the accuracy of a model is high; the coverage also shows high value. This implies that the model is efficient in predicting true contact out of the prediction.

3   Results and Analysis

The performance of the constructed prediction models are evaluated by comparing the prediction to the true contacts information. Measurement is done in terms of accuracy and coverage where accuracy is defined as the total number of correct prediction per total number of predictions while coverage is defined as the total number of correct prediction per total number of true contacts in the protein. The overall accuracy results for all prediction models are shown in Table 2 while for the coverage results are shown in Table 3.

Table 2. Results from different prediction models (Accuracy)

Protein	length	TC	Type	ACCURACY									
				Model 1	Model 2	Model 3	Model 4	Model 5	Model 6	Model 7	Model 8	Model 9	Model 10
1CTJA	89	95	alpha	0.023	0.011	0.180	0.023	0.023	0.124	0.023	0.135	0.000	0.214
1C75A	71	95	alpha	0.170	0.141	**0.338**	**0.085**	0.239	0.352	0.141	0.296	0.056	**0.268**
1CQYA	99	225	beta	0.172	**0.283**	0.131	0.051	0.192	0.131	0.182	0.253	**0.212**	0.121
1BMGA	98	220	beta	0.184	0.163	0.102	0.071	0.255	0.265	0.255	0.163	0.071	0.071
1MWPA	96	197	a+b	0.135	0.010	0.052	0.063	0.146	0.104	0.125	0.135	0.052	0.042
1G2RA	94	126	a+b	**0.394**	0.106	0.170	0.053	0.223	0.362	**0.426**	0.138	0.011	0.043
1CXQA	143	211	a/b	0.287	0.014	0.070	0.021	0.280	0.357	0.280	0.035	0.021	0.021
1F4PA	147	293	a/b	0.320	0.088	0.054	0.061	**0.327**	**0.374**	0.265	0.136	0.027	0.048
1A1HA	85	85	small	0.118	0.012	0.188	0.000	0.235	0.294	0.059	**0.318**	0.012	0.247
1EJGA	46	59	small	0.261	0.044	0.065	0.044	0.152	0.239	0.217	0.065	0.000	0.065
1AA0A	113	63	coil-coil	0.115	0.089	0.177	0.009	0.168	0.257	0.115	0.230	0.044	0.177

Table 3. Results from different prediction models (Coverage)

Protein	Length	TC	Type	COVERAGE									
				Model 1	Model 2	Model 3	Model 4	Model 5	Model 6	Model 7	Model 8	Model 9	Model 10
1CTJA	89	95	alpha	0.0211	0.011	0.168	0.021	0.021	0.116	0.021	0.126	0.000	0.200
1C75A	71	95	alpha	0.126	0.105	**0.253**	**0.063**	0.179	0.263	0.105	0.221	0.042	0.200
1CQYA	99	225	beta	0.076	0.124	0.058	0.022	0.084	0.058	0.080	0.111	**0.093**	0.053
1BMGA	98	220	beta	0.082	0.073	0.046	0.032	0.114	0.118	0.114	0.073	0.032	0.032
1MWPA	96	197	a+b	0.066	0.005	0.025	0.031	0.071	0.051	0.061	0.066	0.025	0.020
1G2RA	94	126	a+b	**0.294**	0.079	0.127	0.040	0.167	0.270	**0.318**	0.103	0.0080	0.032
1CXQA	143	211	a/b	0.194	0.010	0.047	0.014	0.190	0.242	0.190	0.024	0.014	0.014
1F4PA	147	293	a/b	0.160	0.044	0.027	0.031	0.164	0.188	0.133	0.068	0.014	0.024
1A1HA	85	85	small	0.118	0.012	0.188	0.000	0.235	0.294	0.059	0.318	0.012	0.247
1EJGA	46	59	small	0.203	0.034	0.051	0.034	0.119	0.186	0.170	0.051	0.000	0.051
1AA0A	113	63	coil-coil	0.206	**0.159**	0.159	0.016	**0.302**	**0.460**	0.206	**0.413**	0.079	**0.318**

Based on the results reviewed, and also based on the prediction performance data shown in Table 2 and Table 3, accuracy of the contact map prediction is directly correlated to the information or features integrated into the prediction model. This can be seen in this research, the prediction results of model 4, model 9 and model 10 which integrating protein information features as one of the information to predict contact map. However, the results obtained is very low in accuracy and performance is not balance and consistent on all types of proteins. While for model 1, model 5, model 6 and model 7, these models obtained good results among others. This can be clearly seen by observing the average accuracy and coverage obtained as shown in Fig. 4 and Fig. 5. These four models yielded overall consistent results throughout this research, four of this model have similarity where each of the models also implemented local window information as one of the feature. This further implies the effectiveness of the information of local window feature in distinguishing residue contact from protein sequence. Based on the findings from previous researches, performance of the prediction is affected by the

reliability of the information used such as multiple sequence alignment, predicted secondary structure, predicted solvent accessibility and so forth.
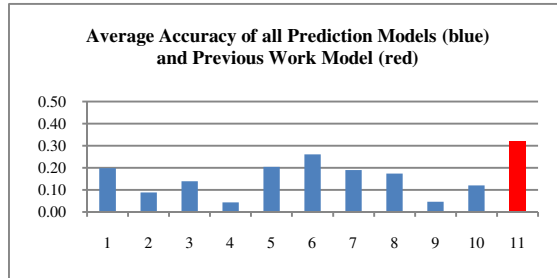

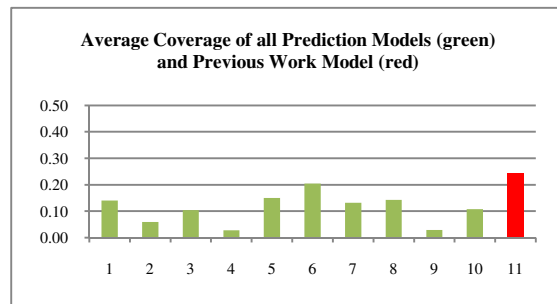**Fig. 4.** Average prediction accuracy of all models (blue) and previous work model (red)

Fig. 5. Average coverage of all models (green) and previous work model (red)

Based on Fig. 4, prediction model 6 manages to get accuracy near the accuracy obtained by the previous work model done by Cheng and Baldi [3]. This shows the significant of the features within the model especially the local window feature which shows significance on model 1, 5, and 7. Besides, based on Fig. 5, the coverage of model 6 is very near to the coverage obtained by previous work model. This shows that significance of the features used in model 6 has a high recall rate on the true contacts of the proteins.
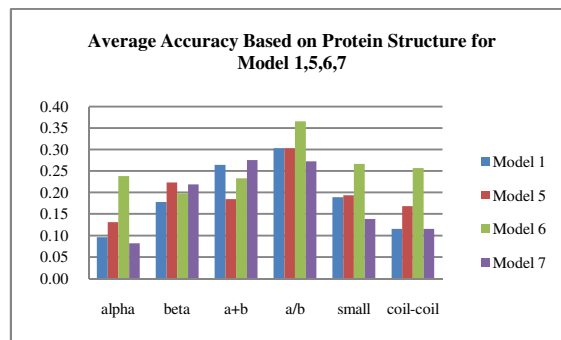

Fig. 6. Average accuracy on different protein structure

Meanwhile, the performance affection in terms of effectiveness of the features used to build the prediction models, the performance also affected by the type of the proteins that used for testing. Fig. 6 shows the average accuracy of model 1, 5, 6, 7 based on different types of protein structure of the tested proteins.

According to Fig. 6, clearly shown that the types of structure such as beta, a+b, and a/b tend to be predicted with higher accuracy.   Refer to the research done previously, the contacts that within beta-sheets are predicted with higher accuracy than contacts that between alpha helix and a beta strands or between alpha helix [4, 8]. This is probably because of the strong restraints between beta-strands such as hydrogen bond gives the increased accuracy. This are shown more clearly in Fig. 7 by average the accuracies obtained for all models based on different type of structure.
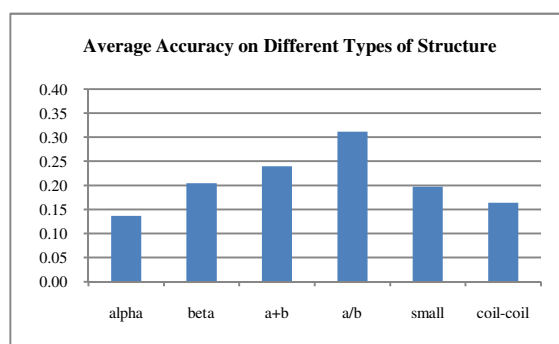

Fig. 7. Average accuracy on different types of structure

4   Conclusion

Different with previous research, this research concentrate on the determination and analysis of the effectiveness of the features used in protein contact map prediction to contribute and improve protein contact map prediction which the main advantage of this research that is not so concentrated in previous research. Even though the accuracy achieved by the constructed prediction models is lower than previous research, however, based on the results that obtained by combination of two features, highest average results achieved is 81% of the average accuracy from previous research (5 features). This implies that the feature information (2 features) used in model 6 is efficient in predicting protein contact map, and indirectly implies the existence of unnecessary or inefficient features. This also shortens the execution time of the process with more experiments can be conducted. However, due to the time constraint, this research is done using combination of two features, more variety of combination can be made with implement of more features can be done in future. Therefore, in this research, with the construction of the multiple prediction models with different combination of features, effectiveness of the features that affect the performance of the prediction are identified, and further improve the knowledge regard to the effective information to be used in protein residue contact prediction.

We believe that, in order to further increase the accuracy of the predictions for all kind of proteins, a more informative feature of proteins is needed even combination of informative features that able to distinct the contacts among residues. This research had shown that the use of local window feature in the prediction model yield decent results among others, while on the other hand, this research also shows that combination of local window feature and segment average information (model 6) produce balance results among all structures. By the identification of these information, through combining others effective features with the one shown in this research, it is believed that this can help to improve the accuracy of the prediction.

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